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INFORMATION DISCLOSURE STATEMENT BY APPLICANT

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First Named Inventor	Jun HAGIHARA
Art Unit	3664
Examiner Name	Spencer D PATTON
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U.S. PATENTS						
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	1	05-143106	JP	Α	1993-06-11	Nikon Corp.		Abstract

		NON PATENT LITERATURE ROCUMENTS			
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Examiner Initials*	Cite No	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city, and/or country where published.	T ⁵		
	1	Supplemental European Search Report for Application No. 03736051.8-1239/1550924, dated March 8, 2010.	Υ		
	2	Michael THUMMEL, et al.; "Control of Robots with Elastic Joints based on Automatic Generation of Inverse Dynamics Models"; Proceedings of the 2001 IEEE/RSI Intl conference on Intelligent Robots and Systems; October 29 - Nov 3, 2001; Vol. 2, pages 925 - 930; XP010571815; ISBN: 978-0-7803-6612-1	Υ		
	3	Hendrik VAN BRUSSEL, et al.; "Accurate Motion Controller Design Based on an Extended Pole Placement Method and Disturbance Observer"; CIRP ANNALS - Manufacturing Technology; Int. Inst. For Production Engineering Research; 1994; Vol. 43 No. 1, pages 367-375, XP002570457	Υ		

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